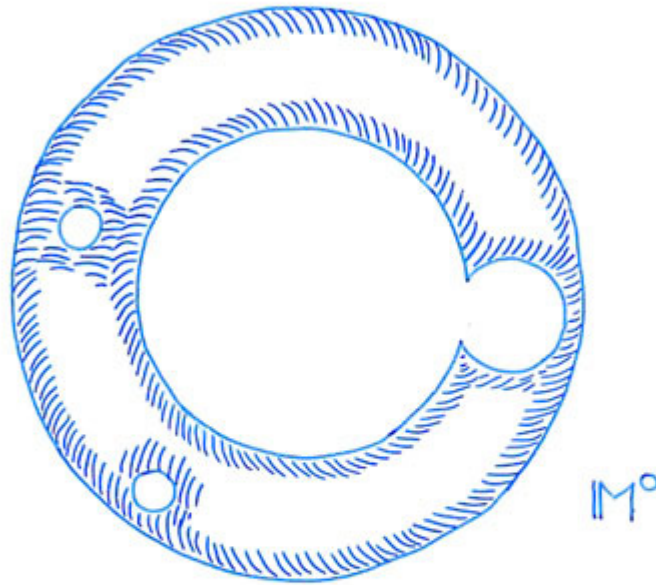


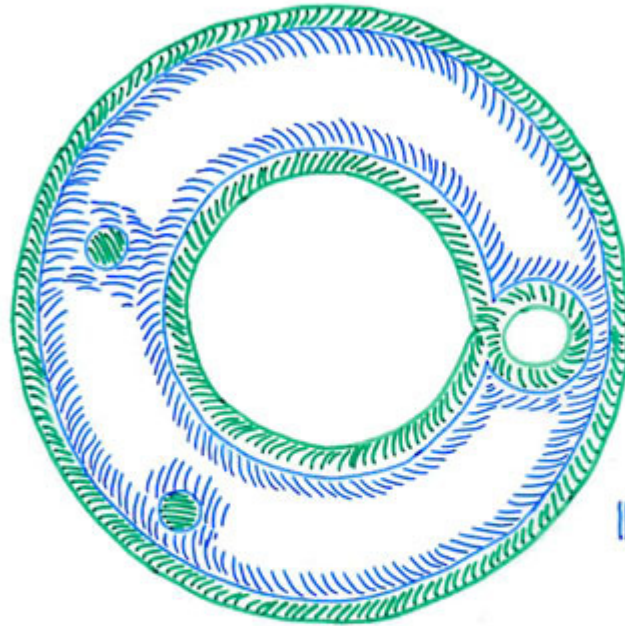
STEPS INTO COMPUTATIONAL ALGEBRAIC TOPOLOGY

- I. TOPOLOGICAL PERSISTENCE
- II. STABLE DIAGRAMS
- III. APPLICATIONS

I.1 SMALL 'N' BIG HOLES

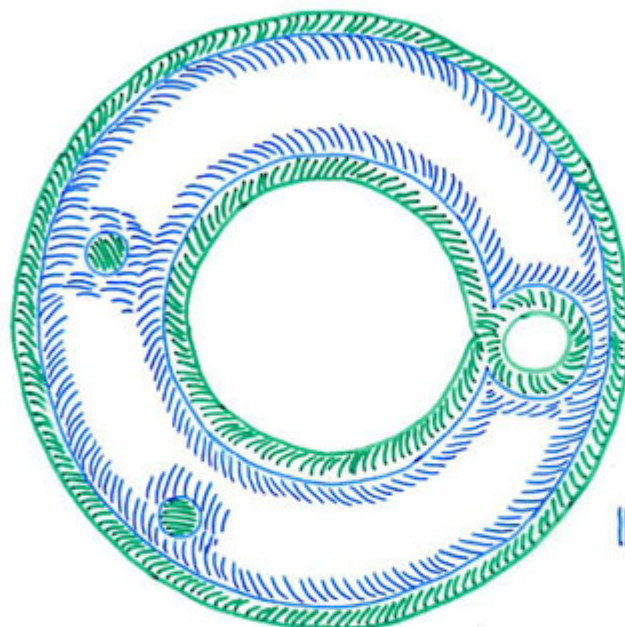


I.1 SMALL 'N' BIG HOLES



$$M^0 \subseteq M^{+\epsilon}$$

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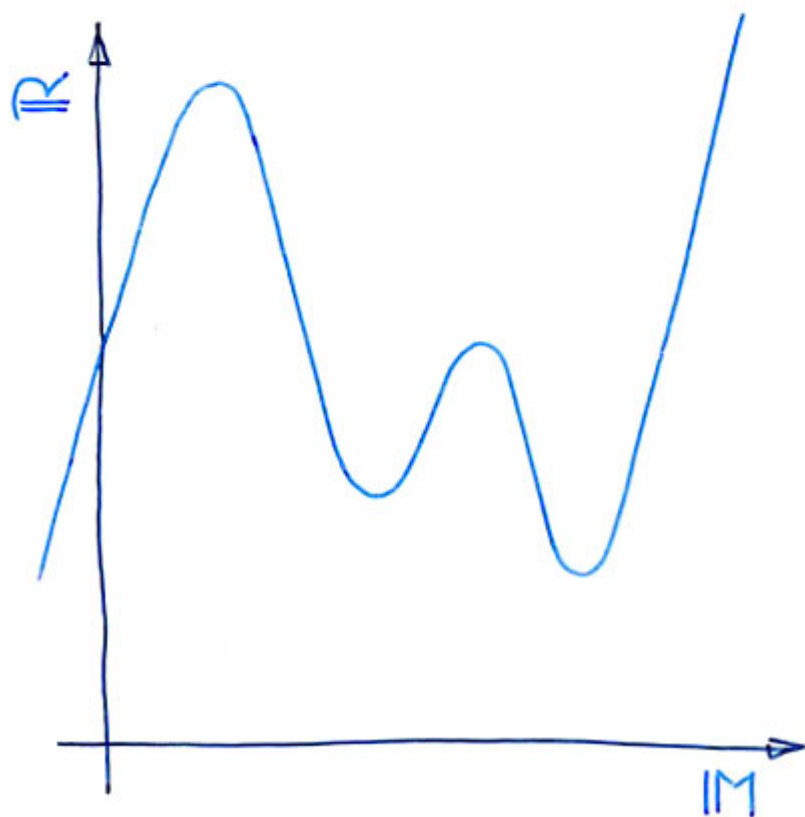
	$H_1(M^0)$	$H_1(M^{+\epsilon})$	F_0^ϵ
dim	3	2	1

where $F_0^\epsilon = \text{im}(H_1(M^0) \rightarrow H_1(M^{+\epsilon}))$.

I.2 FUNCTION

$$f: \mathbb{M} \rightarrow \mathbb{R}$$

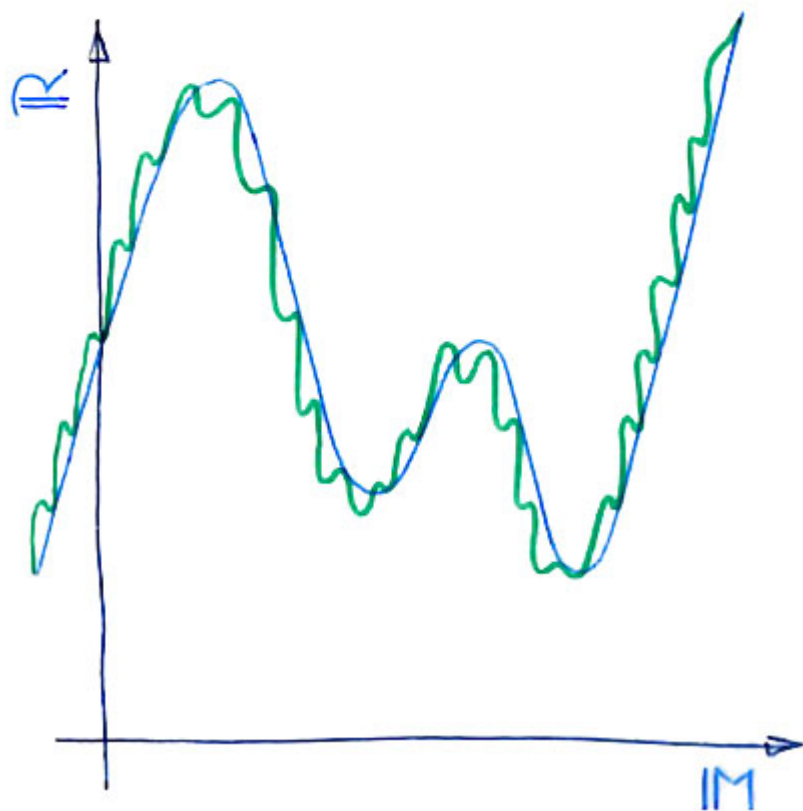
$$\mathbb{M}^x = f^{-1}(-\infty, x]$$



I.2 FUNCTION

$$f: \mathbb{M} \rightarrow \mathbb{R}$$

$$\mathbb{M}^x = f^{-1}(-\infty, x]$$



I.3 PERSISTENT HOMOLOGY

$$\dots \subset M^x \subset \dots \subset M^y \subset \dots$$

$$\dots \rightarrow H^x \rightarrow \dots \rightarrow H^y \rightarrow \dots$$

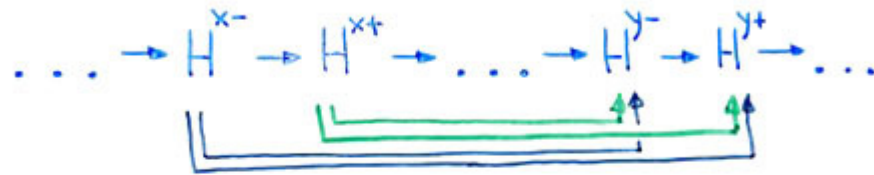
persistent homology groups are

$$F_x^y = \text{im}(H^x \rightarrow H^y) \subseteq H^y$$

persistent Betti numbers are

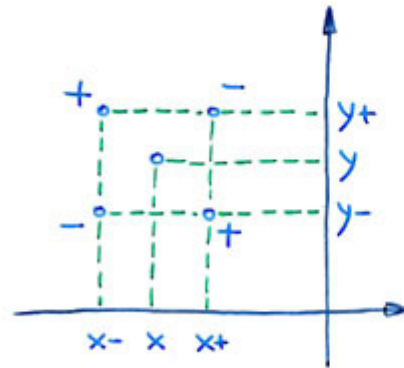
$$\beta_x^y = \dim F_x^y$$

I.4 CRIT. VALUE PAIRS

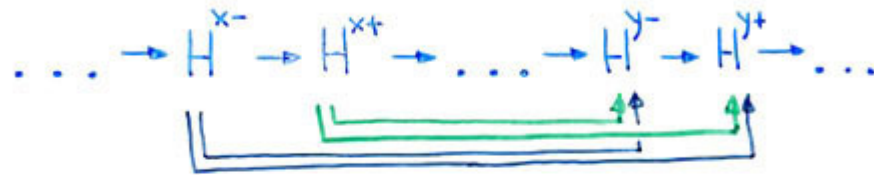


multiplicity is

$$\mu_x^y = \beta_{x-}^{y+} - \beta_{x-}^{y-} - \beta_{x+}^{y+} + \beta_{x+}^{y-}$$

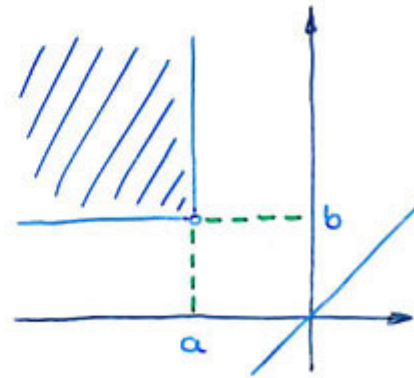
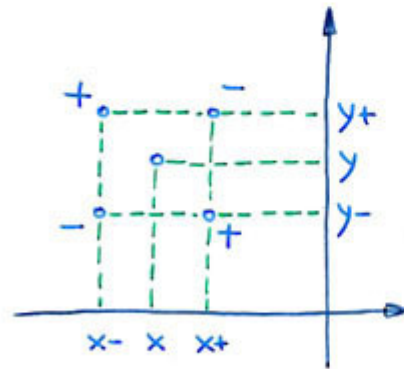


I.4 CRIT. VALUE PAIRS



multiplicity is

$$\mu_x^y = \beta_{x-}^{y+} - \beta_{x-}^{y-} - \beta_{x+}^{y+} + \beta_{x+}^{y-}$$



$$\beta_a^b = \sum_{x \in a \leq x \leq b \leq y} \mu_x^y$$

I.2 FUNCTION

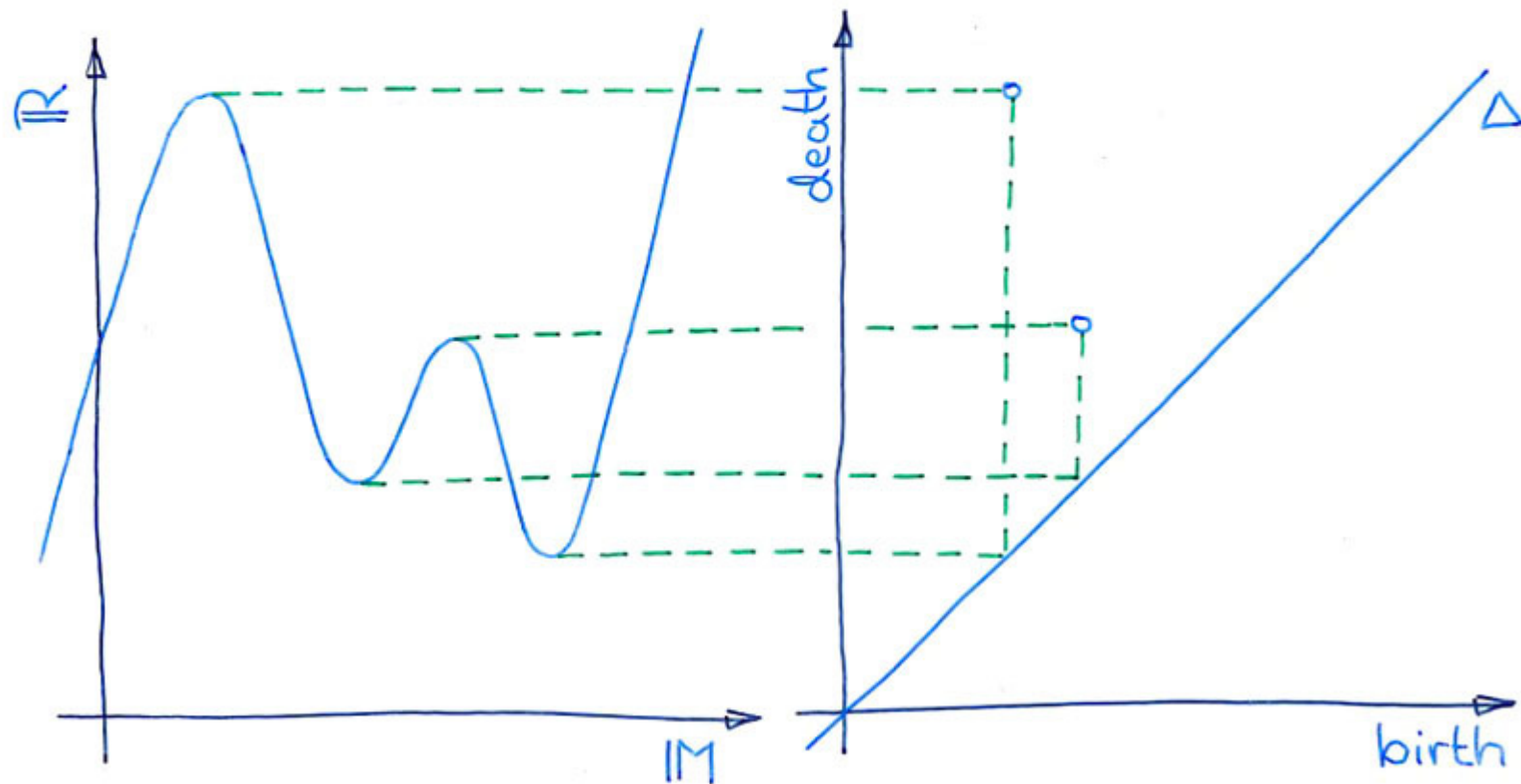
$$f: \mathbb{M} \rightarrow \mathbb{R}$$

$$\mathbb{M}^x = f^{-1}(-\infty, x]$$

II.1 DIAGRAM

persistence diagram of f is

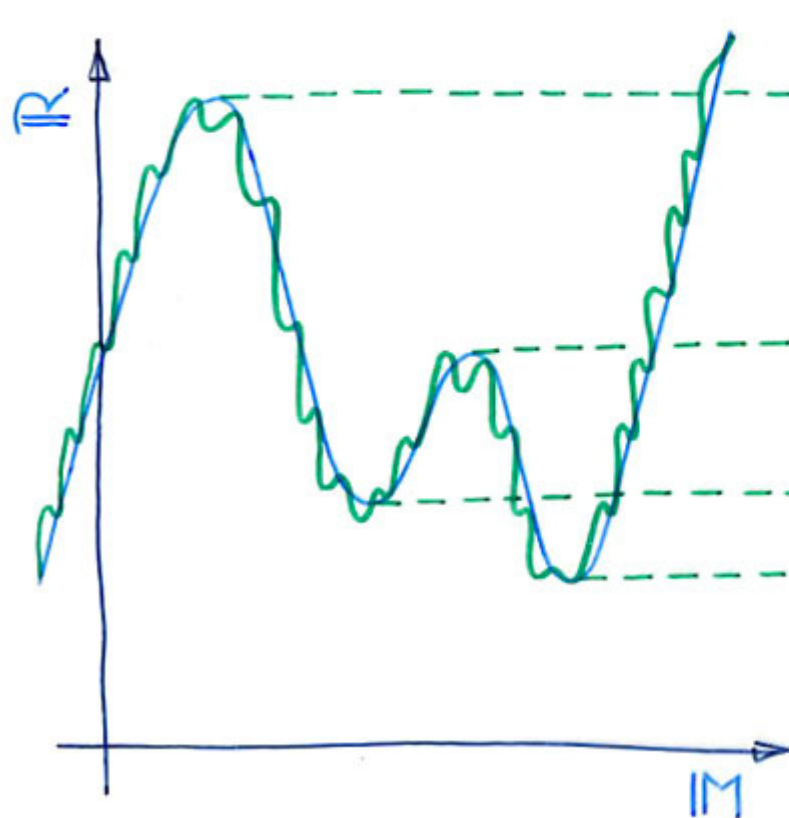
$$D(f) = \Delta \cup \{\text{bd-pairs}\}$$



I.2 FUNCTION

$$f: \mathbb{M} \rightarrow \mathbb{R}$$

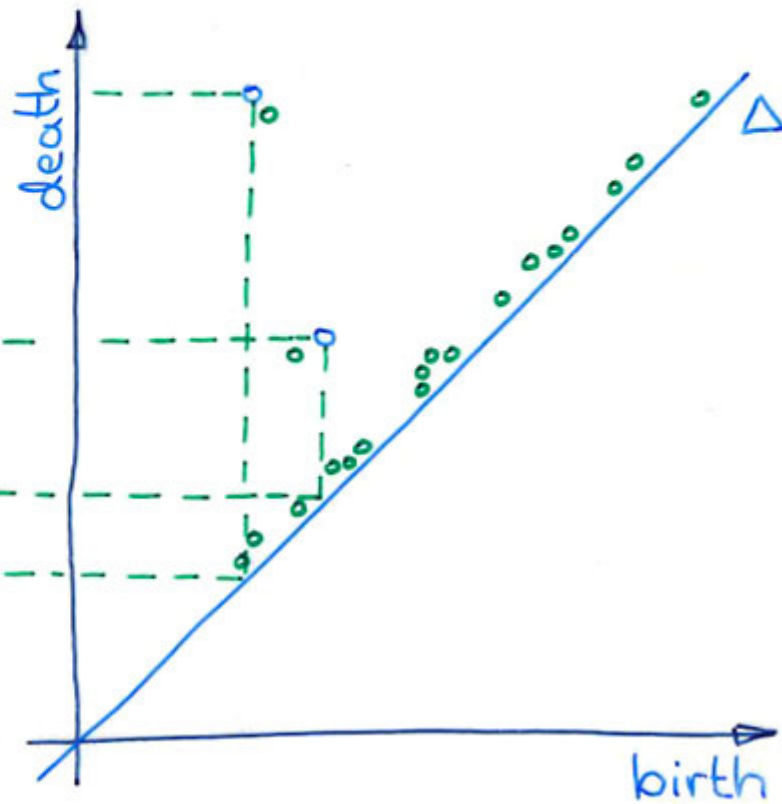
$$\mathbb{M}^x = f^{-1}(-\infty, x]$$



II.1 DIAGRAM

persistence diagram of f is

$$D(f) = \Delta \cup \{\text{bd-pairs}\}$$



II.2 METRICS

L_∞ -distance between functions

is

$$\|f - g\|_\infty = \sup_{x \in M} |f(x) - g(x)|.$$

Fréchet bottleneck distance

between diagrams is

$$d_F(D(f), D(g)) = \inf_{\gamma: D(f) \rightarrow D(g)} \sup_{p \in D(f)} \|p - \gamma(p)\|_\infty.$$

II.3 STABILITY THEOREM

THM [Cohen-Steiner, E, Harer 2004]

M is triangulable space,

$f, g: M \rightarrow \mathbb{R}$ are continuous
and tame.

Then

$$d_F(D(f), D(g)) \leq \|f - g\|_\infty.$$

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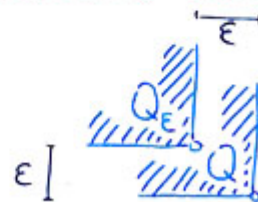
Then

$$d_F(D(f), D(g)) \leq \|f - g\|_\infty.$$

\Rightarrow **Q LEMMA** [Robins 1999]

$$\epsilon = \|f - g\|_\infty$$

Then

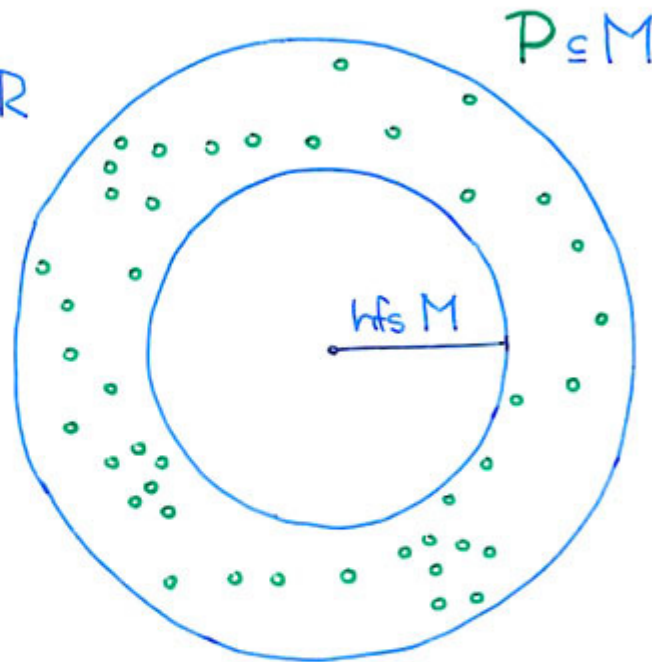


$$\#(D(f) \cap Q_\epsilon) \leq \#(D(g) \cap Q).$$

III.1 HOMOMOLOGY ESTIMATION

$$d^M, d^P: \mathbb{R}^d \rightarrow \mathbb{R}$$

distance
function of
 M, P



hom. feature size of d^M is

$hfs M = \text{min. pos. hom. crit. value}$

$M_x^y, P_x^y \dots$ persistent hom. groups

III.2 APPROXIMATION

THM. $d(P, M) < \epsilon < \frac{hfs M}{4}$.

Then

$$H(M) = P_{\epsilon}^{3\epsilon}.$$

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PROOF. $\|d^P - d^M\| < \epsilon$.

Q Lemma implies

$$\dim M_0^{4\epsilon} \leq \dim P_{\epsilon}^{3\epsilon} \leq \dim M_{2\epsilon}^{2\epsilon}$$
$$= \quad =$$

because $4\epsilon < \text{hfs } M$

$$\dim(H(M)) = \dim M_0^0 = \dim M_0^{4\epsilon}$$

□

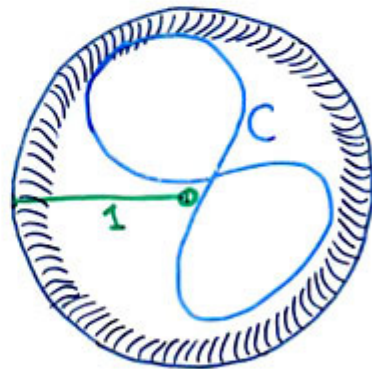
III.3 CURVES

$$K(C) = \int K(s) ds$$

$$L(C) = \frac{1}{2} \int \chi(h_n C) dh$$

Fary's THM

$$L(C) \leq K(C).$$



THM $|L_1 - L_2| \leq (K_1 + K_2 - 2\pi) \cdot d_F(C_1, C_2).$

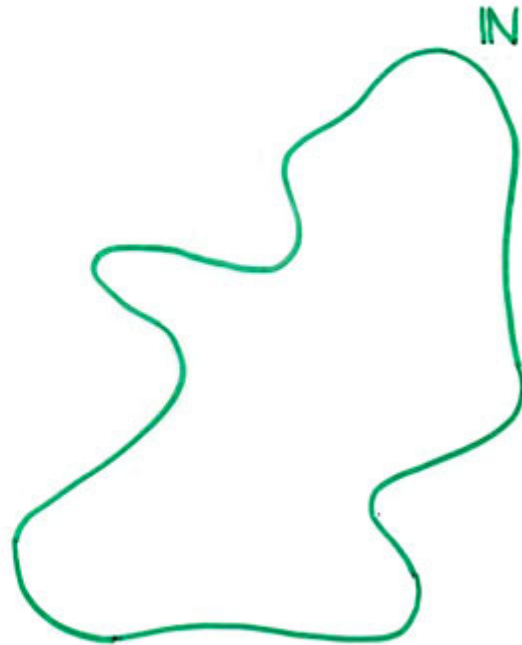
III.4 SURFACES

$$\begin{aligned} G(S) &= \int |K_1(s) \cdot K_2(s)| ds \\ &= 2\pi (\text{avg. \# crit. pts. of height } f.) \end{aligned}$$

$$\begin{aligned} H(S) &= \frac{1}{2} \int (K_1(s) + K_2(s)) ds \\ &= \int \chi(h \cap \bar{S}) dh \end{aligned}$$

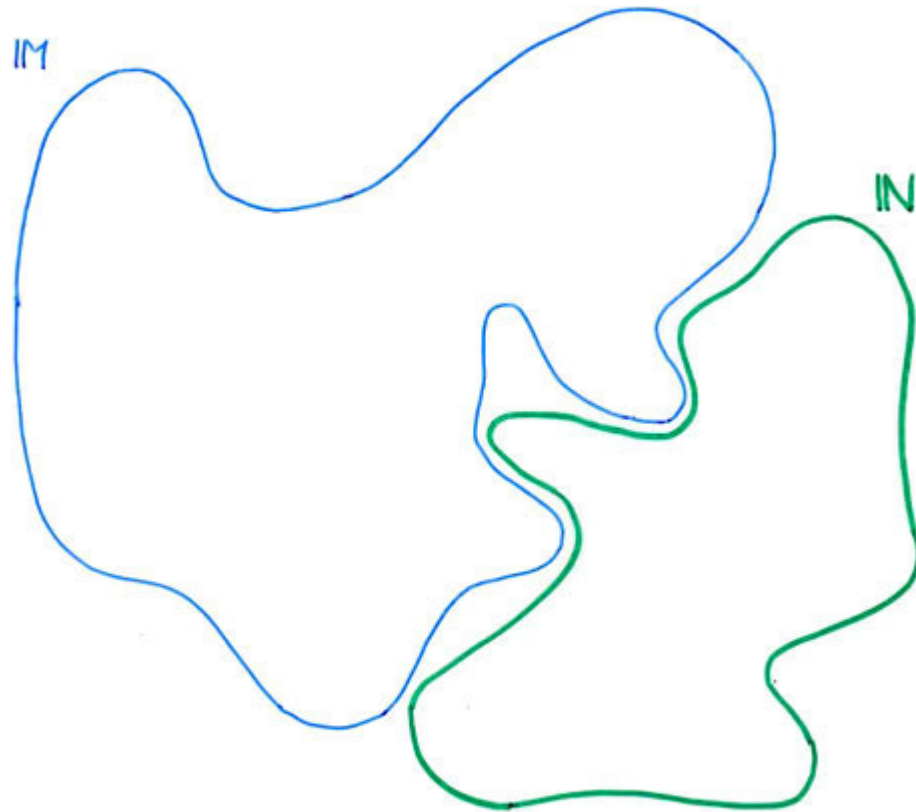
THM. $|H_1 - H_2| \leq (G_1 + G_2 - 2\pi(1+g)) \cdot d_F(\bar{S}_1, \bar{S}_2).$

III.5 PROTEIN INTERACTION



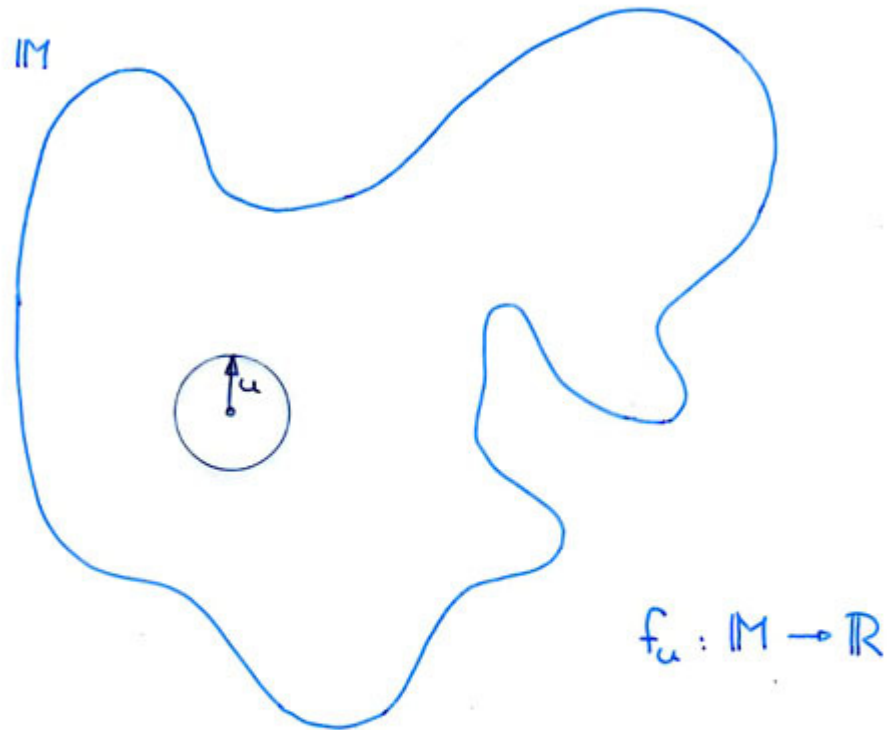
docking = comput. prediction of
interacting configuration

III.5 PROTEIN INTERACTION



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III.6 HEIGHT 'N' ELEVATION

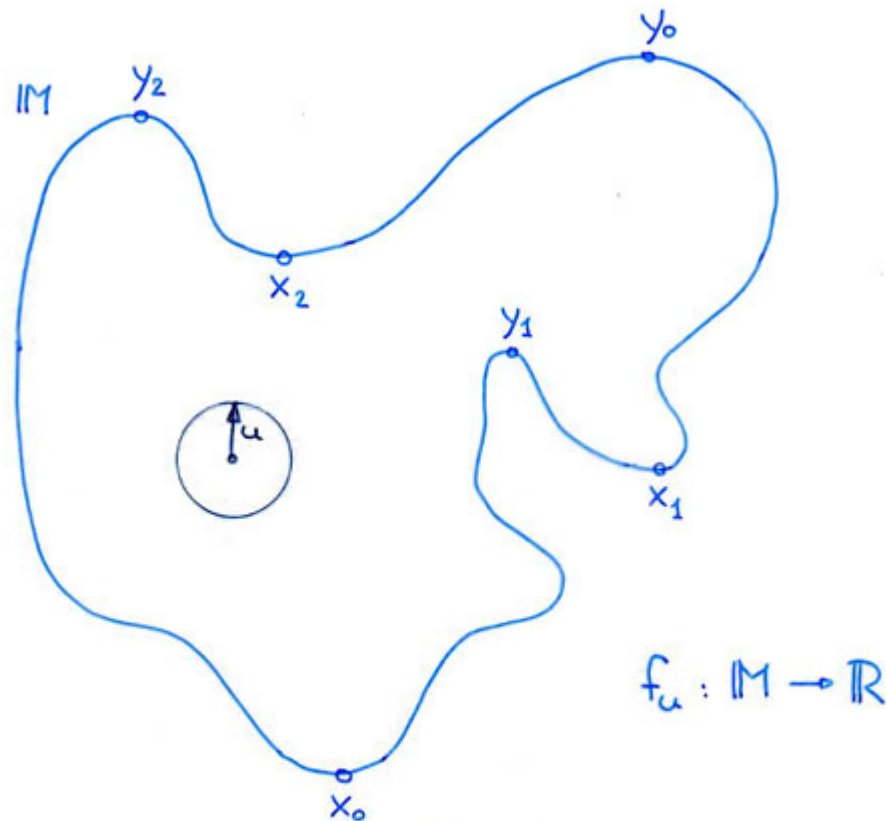


elevation is $E : M \rightarrow \mathbb{R}$ defined by

$$E(x) = |f_u(x) - f_u(y)| \quad \text{with}$$

- (i) $u = \pm n_x = \pm n_y$, (ii) x, y paired.

III.6 HEIGHT 'N' ELEVATION

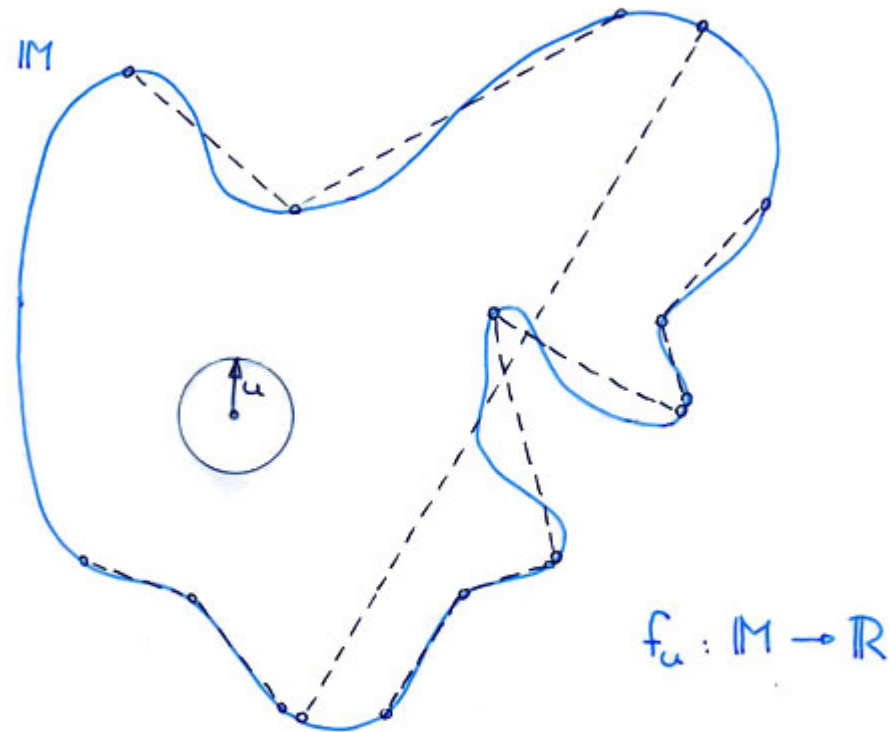


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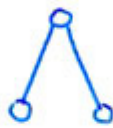
- (i) $u = \pm n_x = \pm n_y$, (ii) x, y paired.

III.7 MAXIMA IN \mathbb{R}^3

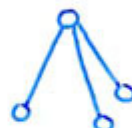
four types



1-



2-



3-



4-legged

To align IM with IN ,
fit legs in pairs to define
rigid motions.